# **Improving Transferability of Representations** via Augmentation-Aware Self-Supervision

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# TL; DR. Learning augmentation-aware information by predicting the difference between two augmented samples improves the transferability of representations for various downstream tasks.

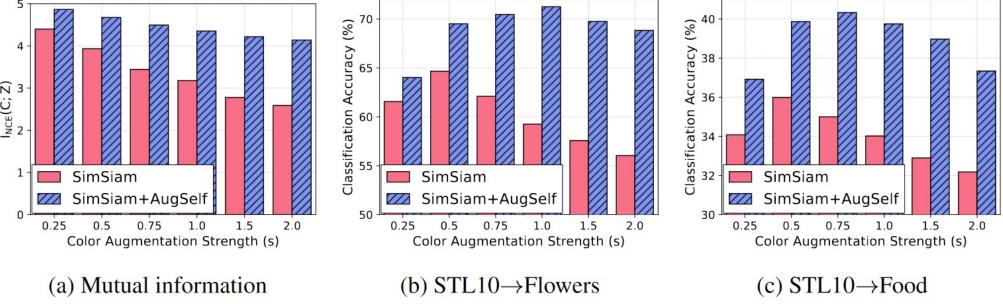
# **Background & Motivation**

Self-supervised learning (SSL) learns representations via a pretext task that requires to predict self-supervision constructed from only input signals. Recent SSL methods often aim at learning invariance to data augmentations

- Contrastive methods (e.g., MoCo [1], SimCLR [2])
- Negative-free methods (e.g., BYOL [3], SimSiam [4])
- Clustering-based methods (e.g., SwAV [5])

**Question:** is learning invariance to a given set of augmentations always beneficial to representation learning? To answer this question,

- Pretrain ResNet-18 on STL10 with varying color jittering strength s.
- Compute mutual information between the learned representation Z=f(x) and color information C(x) encoded by color histograms.
- Transfer the learned representation to color-sensitive downstream tasks.



#### **Observations:**

- Stronger color augmentations  $\Rightarrow$  color-relevant information loss
- Less color information  $\Rightarrow$  performance drop in color-sensitive tasks

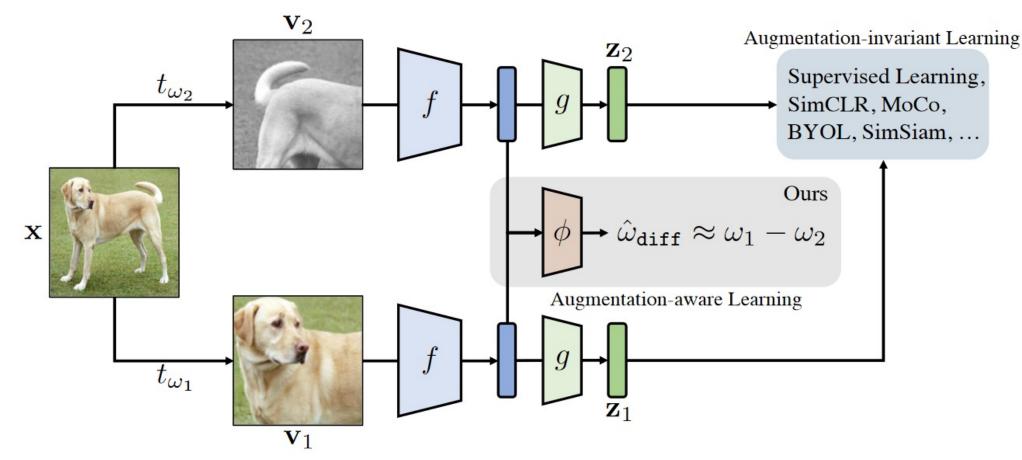
**Research Question:** how to prevent the information loss comes from learning the invariance?

# **Summary of Contribution**

- For learning augmentation-aware information, we suggest to optimize an auxiliary self-supervised loss (**AugSelf**) that learns to predict difference between augmentation parameters of two randomly augmented samples.
- Extensive experiments demonstrate that (1) **AugSelf** can improve learned representations' transferability for various downstream tasks, and also (2) **AugSelf** can be easily incorporated with recent SSL methods with a negligible additional training cost.

## Method

**Notation.** x is an original input image.  $t_{\omega}$  is an augmentation function parameterized by  $\omega$ .  $\mathbf{v} = t_{\omega}(\mathbf{x})$  is the augmented sample of  $\mathbf{x}$  by  $t_{\omega}$ . f is a CNN feature extractor such as ResNet. g is a projection MLP that is widely used in recent SSL methods [1-5].  $\phi$  is a prediction MLP for AugSelf.



For learning augmentation-aware information, we learn to predict the difference between two augmented samples. Formally, auxiliary augmentation-aware self-supervised loss (AugSelf) is defined by

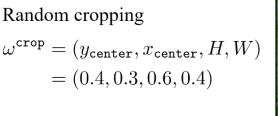
 $\mathcal{L}_{\texttt{AugSelf}}(\mathbf{x}, \omega_1, \omega_2; \theta) = \sum_{\texttt{aug} \in \mathcal{A}_{\texttt{AugSelf}}} \mathcal{L}_{\texttt{aug}}(\phi_{\theta}^{\texttt{aug}}(f_{\theta}(\mathbf{v}_1), f_{\theta}(\mathbf{v}_2)), \omega_{\texttt{diff}}^{\texttt{aug}})$ where  $\omega_{\rm diff}^{\rm aug}$  is the difference between augmentation-specific parameters.

### Benefits of AugSelf: it can ...

- preserve augmentation-aware information for downstream tasks
- be easily incorporated with [1-5] thanks to its self-supervision design

In this work, we mainly use  $\mathcal{A}_{AugSelf} = \{crop, color_jitter\}$  and MSE for  $\mathcal{L}_{aug}$ .







 $(\lambda_{\texttt{bright}}, \lambda_{\texttt{contrast}}, \lambda_{\texttt{sat}}, \lambda_{\texttt{hue}})$ = (0.3, 1.0, 0.8, 1.0)



# References

[1] He et al., Momentum Contrast for Unsupervised Visual Representation Learning, CVPR 2020

- [2] Chen et al., A Simple Framework for Contrastive Learning of Visual Representations, ICML 2020
- [3] Grill et al., Bootstrap your own latent: A new approach to self-supervised Learning, 2020
- [4] Chen & He, Exploring Simple Siamese Representation Learning, 2020

[5] Caron et al., Unsupervised Learning of Visual Features by Contrasting Cluster Assignments, NIPS 2020



## Experiment

SelfAug improves the transferability of representations in various standard (first table) and few-shot (second table) downstream classification tasks

Method	CIFAR10	CIFAR10	00 Food	MIT67	Pets	Flowers	Caltech	101 Cars	Aircraft	DTD	SUN397
				ImageNet1	00-pretr	ained Res	Net-50				
SimSiam + AugSelf	86.89 <b>88.80</b>	66.33 <b>70.27</b>	61.48 <b>65.63</b>	65.75 <b>67.76</b>	74.69 <b>76.34</b>	88.06 <b>90.70</b>	84.1 <b>85.3</b>		48.63 <b>49.76</b>	65.11 <b>67.29</b>	50.60 <b>52.28</b>
MoCo v2 + AugSelf	84.60 <b>85.26</b>	61.60 <b>63.90</b>	59.37 <b>60.78</b>	61.64 <b>63.36</b>	70.08 <b>73.46</b>	82.43 <b>85.70</b>	77.2 <b>78.9</b>		<b>41.21</b> 39.47	64.47 <b>66.22</b>	46.50 <b>48.52</b>
Supervised + AugSelf	<b>86.16</b> 86.06	62.70 <b>63.77</b>	53.89 <b>55.84</b>	52.91 <b>54.63</b>	73.50 <b>74.81</b>	76.09 <b>78.22</b>	<b>77.5</b> 77.4		36.78 <b>38.02</b>	61.91 <b>62.07</b>	40.59 <b>41.49</b>
			FC1	00	CUB200		0	Plant Disease			
	Method		(5, 1)	(5, 5)	(5,	1)	(5, 5)	(5, 1)	(5, 5)		
	ImageNet100-pretrained ResNet-50									_	
	SimSiam + AugSelf		6.19±0.36 9.37±0.40	50.36±0.38 55.27±0.38	45.56 <b>48.08</b>		2.48±0.48 <b>5.27±0.46</b>	75.72±0.46 77.93±0.46	89.94±0.31 91.52±0.29		
	MoCo v2 + AugSelf		1.67±0.33 5.02±0.36	43.88±0.38 48.77±0.39	41.67 <b>44.17</b>		5.92±0.47 7.35±0.48	65.73±0.49 <b>71.80±0.4</b> 7	84.98±0.36 87.81±0.33		
	Supervised + AugSelf		3.15±0.33 4.70±0.35	46.59±0.37 48.89±0.38	46.57 <b>47.58</b>		3.69±0.46 5.31±0.45	68.95±0.47 70.82±0.46	88.77±0.30 89.77±0.29		

SelfAug can be incorporated with various SSL methods (STL10 pretraining)

Method	AugSelf (ours)	STL10	CIFAR10	CIFAR100	Food	MIT67	Pets	Flowers
SimCLR [2]	$\checkmark$	84.87 <b>84.99</b>	78.93 80.92	48.94 <b>53.64</b>	31.97 <b>36.21</b>	36.82 40.62	43.18 <b>46.51</b>	56.20 64.31
BYOL [12]	$\checkmark$	86.73 <b>86.79</b>	82.66 83.60	55.94 <b>59.66</b>	37.30 <b>42.89</b>	42.78 <b>46.17</b>	50.21 <b>52.45</b>	66.89 <b>74.07</b>
SWAV [11]	$\checkmark$	82.21 82.57	81.60 <b>82.00</b>	52.00 55.10	29.78 33.16	36.69 <b>39.13</b>	37.68 <b>40.74</b>	53.01 61.69

#### Object localization (blue is ground-truth & red is prediction)

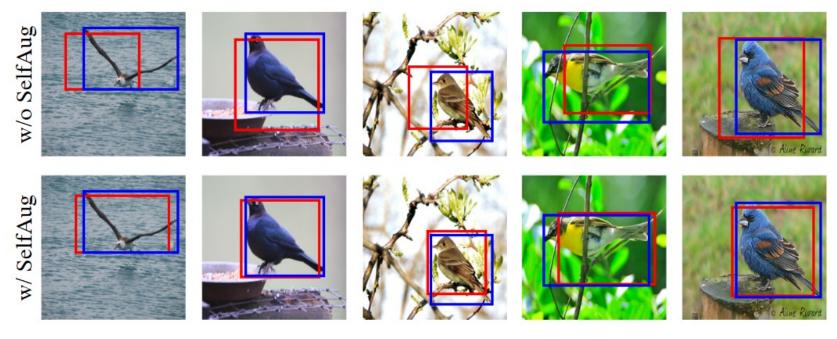


Image retrieval: SimSiam (left) vs SimSiam+AugSelf (right, ours) Nearest neighbors









